# F6400HD, 2-Way Butterfly Valve Resilient Seat, 304 Stainless Steel Disc

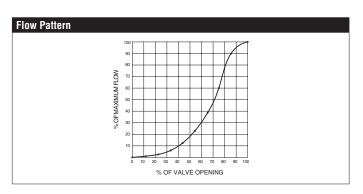








Technical Data	
Service	chilled, hot water, up to 60% glycol
Flow Characteristic	modified equal percentage
Controllable Flow Range	90° rotation
Size [mm]	16" [400]
End Fitting	for use with ANSI Class 125/150 flanges
Body	ductile iron ASTM A536
Body Finish	Epoxy powder coated
Stem Packing	EPDM (lubricated)
Ball Seat	EPDM
Shaft	416 stainless steel
Bushings	RPTFE
Disc	304 stainless steel
Body Pressure Rating [psi]	ANSI 125, standard class B
Number of Bolt Holes	16
Lug Threads	1-8 UNC
Media Temperature Range (Water)	-22°F to 250°F [-30°C to 120°C]
Close-Off Pressure	200 psi
Rangeability	10:1 (for 30° to 70° range)
Maximum Velocity	12 FPS
Cv	16388
Weight	164.2 lb [74.5 kg]
Leakage	0%
Servicing	maintenance free



#### **Product Features**

200 psi (2" to 12") and 150 psi (14" to 24") 0% leakage, Long stem design allows for 2" insulation, Valve face-to-face dimensions comply with API 609 & MSS-SP-67, Completely assembled and tested, Ready for installation.

# **Application**

These valves are designed to meet the needs of HVAC and commercial applications requiring 0% leakage for liquids. Typical applications include chiller isolation, cooling tower isolation, change-over systems, large air handler coil control, bypass and process control applications. The large Cv values provide for an economical control valve solution for larger flow applications. Designed for use in ANSI flanged piping systems.

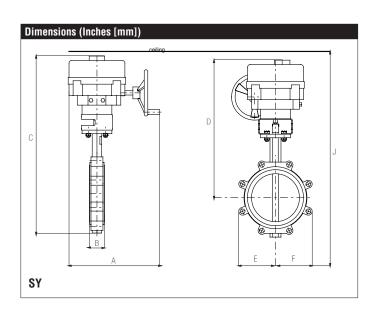
## **Jobsite Note**

Valves should be stored in a weather protected area prior to construction. Complete installation recommendations can be found in Belimo's Installation and Maintenance Instructions for F6/F7... Butterfly Valves.

Flow/Cv								
Cv 10°	Cv 20°	Cv 30°	Cv 40°	Cv 50°	Cv 60°	Cv 70°	Cv 80°	Cv 90°
8	464	983	2130	3797	6282	9942	14913	16388

## **Suitable Actuators**

	Non-Spring
F6400HD	SY6



A	В	C	D	E	F	J
15" [381]	4" [102]	38.70	26.4"	12.3"	[312]	47.32"
		[983.0]	[547]			[1202]









Technical Data	
Power Supply	120 VAC ± 10%, 50/60 Hz
Power Consumption Running	236 W
Transformer Sizing	264 (class 2 power source)
Electrical Connection	terminal block
Overload Protection	thermally protected 135°C cut-out
Operating Range Y	2 to 10 VDC, 4 to 20 mA w/ ZG-R01 (500 $\Omega$ , 1/4 W resistor) between 0% and 100%
Input Impedance	100 k $\Omega$ for 2 to 10 VDC (0.1 mA), 500 $\Omega$ for 4 to 20 mA
Feedback Output U	2 to 10 VDC
Angle of Rotation	90°
Torque	5785 in-lbs [650 Nm] minimum
Duty cycle	75 %
Direction of Rotation (Motor)	reversible with built-in switch
Position Indication	top mounted domed indicator
Manual Override	hand wheel
Running Time (Motor)	28 sec
Internal Humidity Control	resistive heating element
Humidity	5 to 100% RH (UL Type 4)
Ambient Temperature Range	-22°F to 150°F [-30°C to 65°C]
Storage Temperature Range	-40°F to 176°F [-40°C to 80°C]
Housing	NEMA 4X, IP66/67, UL enclosure type 4
Housing Material	die cast aluminum alloy
Gear Train	high alloy steel gear sets, self locking
Agency Listings	ISO, CE, cCSAus
Noise Level (Motor)	<45 dB (A)
Servicing	maintenance free
Quality Standard	ISO 9001
Weight	48.5 lb [22 kg]
Auxiliary Switch	2 x SPDT 3A resistive (0.5A inductive) @ 250 VAC, one set at +10° and one set at 85°

## **Application**

SY Series actuators are fractional horsepower devices, and utilize full-wave power supplies. Observe wire sizing and transformer sizing requirements. Proportional models CANNOT be connected to Belimo direct coupled (AF, AM, GM...etc) actuator power supplies or any type of half-wave device. You MUST use a separate, dedicated transformer or power supply to power the SY actuator. Please do not connect other automation equipment to the dedicated SY supply source. You MUST use four wires (plus a ground) to control a proportional control SY actuator (See SY Wiring Section).





# Modulating, Non-Spring Return, 120 V, for 2 to 10VDC or 4 to 20 mA

## Wiring Diagrams



## X INSTALLATION NOTES



Do not change sensitivity or dip switch setting with power applied.



Power supply Common/Neutral and Control Signal "-"wiring to a common is prohibited. Terminals 4 and 6 need to be wired separately.



Isolation relays must be used in parallel connection of multiple actuators using a common control signal inputs. The relays should be



Isolation relays are required in parallel applications. The reason parallel applications need isolation relays is that the motor uses two sets of windings, one for each direction. When one is energized to turn the actuator in a specific direction a voltage is generated in the other due to the magnetic field created from the first. It's called back EMF. This is not an issue with one actuator because the voltage generated in the second winding isn't connected to anything so there is no flow. On parallel applications without isolation, this EMF voltage energizes the winding it is connected to on the other actuators in the system, the actuators are tying to turn in both directions at once. The EMF voltage is always less than the supply voltage due to the resistance of the windings, so while the actuator still turns in the commanded direction, the drag from the other reduces the torque output and causes overheating.



## WARNING! LIVE ELECTRICAL COMPONENTS!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

